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- Downloaded Baseflight
- Allows simulation and calibration of the quadcopter
- Through the use of Baseflight I confirmed the the motors, gyro, accelerometer, and RC inputs are functioning properly
- I need to figure out how to arm the board, which is required to control the motors

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- Tested the motors through the receiver
- found that only one channel can run the motors
- Tested another receiver and ran into the same problem
- could be something wrong with the speed controllers