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- Disassembled quad copter to examine circuitry
- found no problems
- reassembled
- The AR610 Receiver should be able to control all the motors through the throttle channel
- Re-programmed the flight controller on Baseflight

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- Downloaded Cleanflight (similar to Baseflight)
- Programmed flight controller
- Tested sensors and motors
- Setup arming sequence (could not do on Baseflight)
- Arming Sequence:
Flight mode 0 on Transmitter
and hold upper right on Right stick
and hold Bottom right on left stick
- Tested Receiver and Transmitter independent of Cleanflight and I was able to control all the motors with the Transmitter