

Ball Robot

10/18/16
Pg 15

- Ball
 - 3 motors
 - gyroscope
 - accelerometer
- within IMU
- IR sensors
(for floor, wall, and object recognition)
 - Raspberry pi
 - chassis
 - omni-direction wheels
 - Inertial measurement unit
 - laser range sensor
 - Batteries
 - H-bridge
 - motor driver