

Prosthetic Arm:

- 1.) Smooth motion
- 2.) Plans for EEG + EMG
- EEG - 1kHz, ± 1.5mV
- EMG - ?

} For 11/15/16

Servos:

- Red - 6V (HX-155) Hexfly
- Blue - 6-7.4V (AB05-996HT6+HV) Alturn
- Hand - 5V → higher more torque
- Wrists - 4.6 - 6V - (HS-422) HITAK

position (0-120 is 90°)

Replacing shoulder with DC motor

- look for DC running like servo
- code
- pot. control

11/10

Intelligent Prosthetic Arm: (week update)

- Worked on operating all the servos on the arm

| Realized that shoulder servos would not support weight
| swapped out those servos with DC motor for support
| got it running with code for Arduino

- Currently working on smoothing the movement of the arm and hands. Most servos are running smoothly

- the wrist needs some assistance

- locking shoulder while moving elbow servo