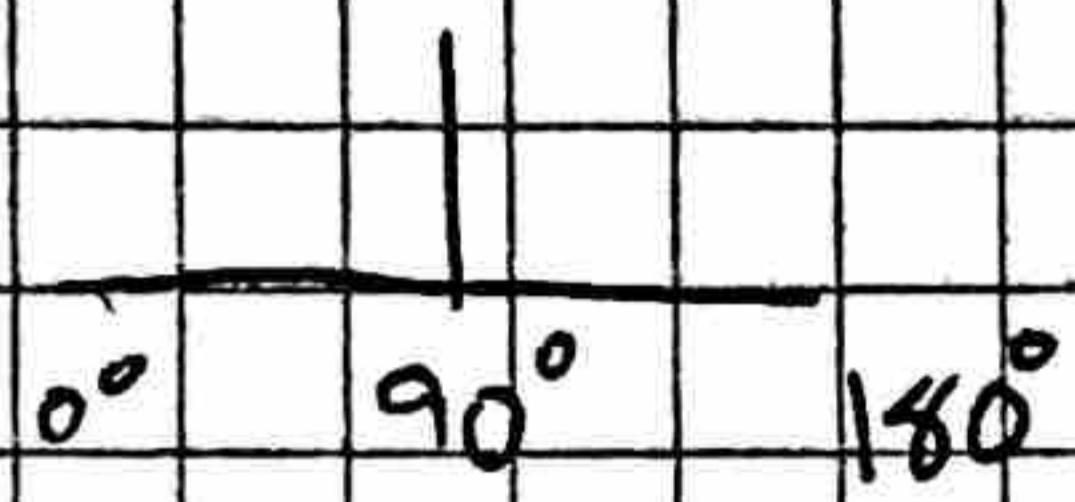


11/29

Wrist servo (1)

straight down $\rightarrow 90^\circ$

\therefore initialize at 90°



Servo 2

Waving motion

$120 - 160^\circ$

Servo 3 (Elbow)

- 120° is on 90° bend
- 30° is straight down

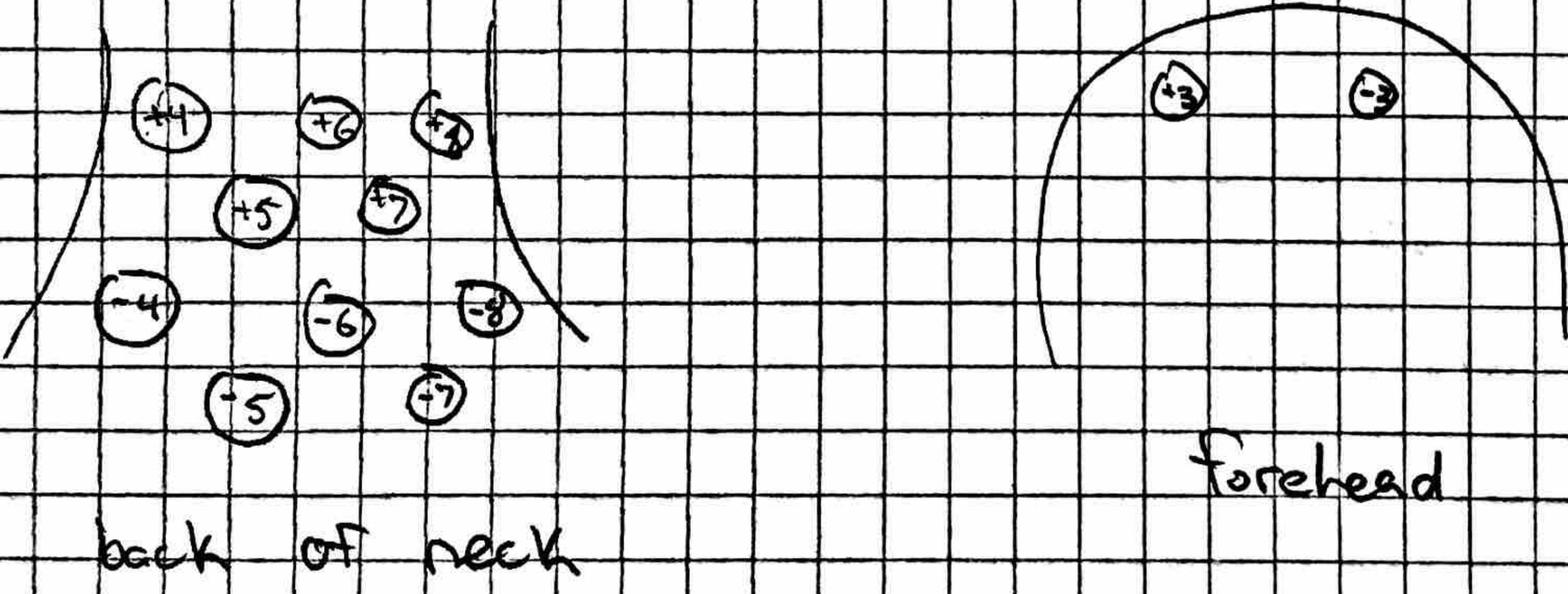
12/1

| | Duty Cycle | issues with running three servos at once - duty cycle |
|-----------------------|----------------------------------|---|
| Servo | 12 | |
| Servo 2 | 9-12 <th data-kind="ghost"></th> | |
| blue Servo 3 elbow | 9 | |

all run at 49.9 Hz

These were tests with Arduino - Next is to apply
to Pi and fix errors

Brain signal Results

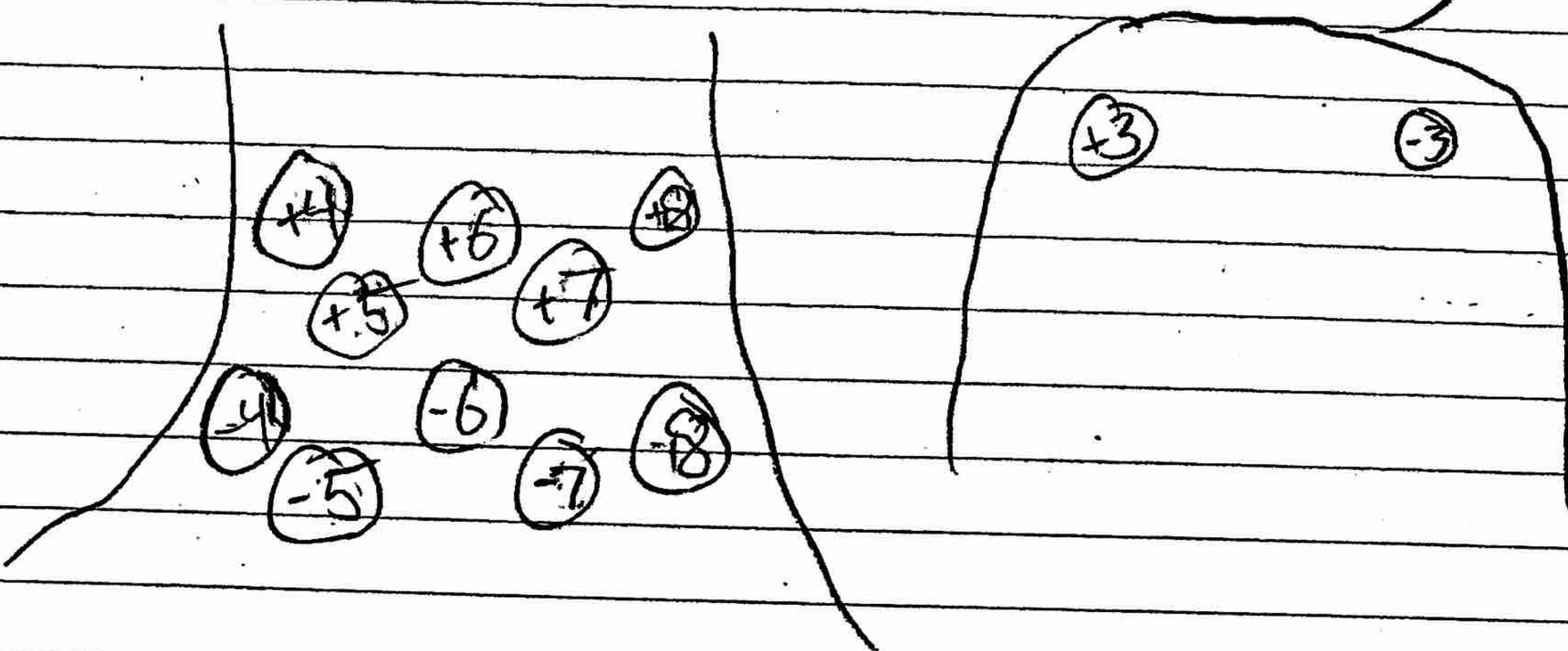


back of neck

forehead

Results show that areas 3 + 5 produce same output
- also include area 7 for other background signals

Brainstem data fishing



Analysis of Brainstem Data

