

9/6/16

Milestones

- 1 Assemble Robot
- 2 Testing + Calibration
- 3 3 types of walking behavior
- 4 Real time info from Kinect to robot
- 5 Robot mimics Kinect monitored walking behavior

Comments

1. Almost Done. Some parts in wrong places.
Time: 5 days - 9/9/16
2. Ensuring everything is properly placed with boxed code
Time: 3 days - 9/12/16
3. Write code that controls robot movements + enter numbers that simulate walking
Time: 14 days - 9/26/16
4. Accept info. from Kinect to previous code
Time: 7 days - 10/3/16
5. Match input to robot movements
Time: 10 days - 10/13/16